

Data Structures and Algorithms

Lecture 22

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2026-03-20 Fri

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1 Agenda

1.1 Graphs

- k-Clique problem for proximity graphs

- Graph Traversals
- Breadth-First Search (BFS)
- Depth-First Search (DFS)

2 k-Clique Problem

- Input: A simple undirected graph $G = (V, E)$
- Question: Does there exist a clique of size k in G ?

Q. What is the time complexity of the k -Clique problem for

- unit disk graphs
- unit interval graphs

Hint: A linear scan is useful for the 1D problem. For the $2n$ critical points (the two end points per interval) maintain a depth vector that denotes the number of intervals that contain critical point i .

- Takeaway: Given the problem we want to solve (e.g., k -Clique problem) and special class of input graph (e.g., unit interval graphs), it may be more useful to avoid the generic data structures (e.g., adjacency list/matrix) to represent the input graph, and use something more specialized (e.g., depth vector).

3 Graph Traversals

- Systematically visit every vertex and edge of a graph
- Two fundamental strategies: BFS and DFS
- Both run in $\Theta(V + E)$ time (on adjacency list representation)
- Basis for almost all graph algorithms

4 Breadth-First Search (BFS)

4.1 The Idea

Given a source vertex s , explore vertices in order of their **distance** from s .

- First visit all vertices at distance 1 from s
- Then all vertices at distance 2
- And so on — like ripples spreading outward

4.2 Data Structure: Queue (FIFO)

- Vertices to be explored are kept in a queue
- ENQUEUE: add to back; DEQUEUE: remove from front
- Ensures vertices are processed in non-decreasing order of distance from s

5 Depth-First Search (DFS)

5.1 The Idea

Explore as **deep** as possible before backtracking.

- From a vertex u , recursively visit an unvisited neighbor v
- When no unvisited neighbors remain, backtrack to the parent
- Continue until all vertices are visited

5.2 Data Structure: Stack (LIFO)

- Recursive implementation uses the **call stack** implicitly
- Iterative version uses an explicit stack
- Unlike BFS: does NOT necessarily find shortest paths

5.3 Timestamps

DFS records two timestamps per vertex (CLRS):

- $u.d$: **discovery time** — when u is first seen (grayed)
- $u.f$: **finish time** — when u 's adjacency list is fully explored (blackened)
- $1 \leq u.d < u.f \leq 2|V|$

6 Applications of BFS and DFS

6.1 Shortest Paths in Unweighted Graphs

BFS from s computes $v.d = \delta(s, v)$ for all vertices v reachable from s .

- Works because BFS explores vertices in non-decreasing order of distance.
- The BFS tree gives the actual shortest paths (trace back via $v.\pi$).
- **Limitation:** only works for unweighted (or unit-weight) graphs.

6.2 Connected Components

To find all connected components of an undirected graph:

```
CONNECTED-COMPONENTS(G)
```

1. for each vertex u in $G.V$
2. $u.component = NIL$
3. $comp = 0$
4. for each vertex u in $G.V$
5. if $u.component == NIL$
6. $comp = comp + 1$
7. BFS(G, u) // or DFS
8. // mark all visited vertices with $comp$

Time: $\Theta(V + E)$.

6.3 Bipartiteness Testing

A graph G is **bipartite** iff it contains no odd-length cycle.

IS-BIPARTITE(G)

```
1. for each vertex  $u$  in  $G.V$ 
2.      $u.color = WHITE$ 
3. for each vertex  $s$  in  $G.V$ 
4.     if  $s.color == WHITE$ 
5.          $s.color = RED$ 
6.         ENQUEUE( $Q, s$ )
7.     while  $Q$  not empty
8.          $u = DEQUEUE(Q)$ 
9.         for each  $v$  in  $G.Adj[u]$ 
10.            if  $v.color == WHITE$ 
11.                 $v.color = opposite(u.color)$ 
12.                ENQUEUE( $Q, v$ )
13.            elseif  $v.color == u.color$ 
14.                return FALSE // odd cycle found
15. return TRUE
```

BFS 2-colors the graph (RED/BLUE). If a conflict arises, an odd cycle exists.

6.4 Cycle Detection

A directed graph G has a cycle iff DFS finds a **back edge**.

Proof sketch:

- (\Rightarrow) If G has a cycle $v_0 \rightarrow v_1 \rightarrow \dots \rightarrow v_k \rightarrow v_0$, then DFS will discover v_0 before v_k finishes, so (v_k, v_0) is a back edge.
- (\Leftarrow) A back edge (u, v) with v an ancestor of u directly gives a cycle.

For undirected graphs: a back edge also reveals a cycle (any non-tree edge is a back edge in undirected DFS).